

On Unbalanced Optimal Transport: An Analysis of Sinkhorn Algorithm

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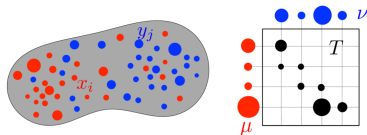
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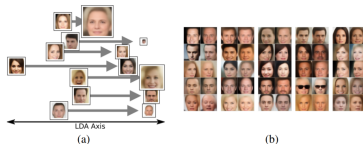
Unbalanced optimal transport: Introduction



Finding an optimal plan to transport between two measures with the same mass (OT) or different masses (UOT)¹.



UOT application: Modeling the growth and the death of cells [Schiebinger et al., 2019].



UOT application: Image transfer [Yang and Uhler, 2019].

¹<https://optimaltransport.github.io/slides/>

Unbalanced optimal transport: Formulation

- $\mathbf{a} \in \mathbb{R}_+^n$, $\mathbf{b} \in \mathbb{R}_+^m$ are two *non-negative* vectors with positive, constant masses $\alpha = \sum_i \mathbf{a}_i$, $\beta = \sum_j \mathbf{b}_j$
- $C \in \mathbb{R}_+^{n \times m}$ is a non-negative cost matrix
- τ is a positive constant

UOT problem

The unbalanced optimal transport (UOT) problem reads

$$\min_{X \in \mathbb{R}_+^{n \times m}} f(X) := \langle C, X \rangle + \tau \mathbf{KL}(X \mathbf{1}_n \| \mathbf{a}) + \tau \mathbf{KL}(X^\top \mathbf{1}_m \| \mathbf{b}).$$

Remark

When $\alpha = \beta$ and $\tau \rightarrow \infty$, this becomes the standard optimal transport (OT) problem.

- Approximating the UOT problem: replace the positivity constraints with an entropy barrier $H(X) = \sum_{i,j=1}^n X_{ij}(\log(X_{ij}) - 1)$.

Entropic UOT Problem

The entropic UOT problem reads

$$\min_{X \in \mathbb{R}_+^{n \times m}} g(X) := \langle C, X \rangle - \eta H(X) + \tau \mathbf{KL}(X \mathbf{1}_n \| \mathbf{a}) + \tau \mathbf{KL}(X^\top \mathbf{1}_m \| \mathbf{b}).$$

Property

For $\eta > 0$, the entropic UOT problem is strongly convex.

Dual function

The solution to the entropic UOT problem is also the optimal solution of the dual function

$$\min_{u, v \in \mathbb{R}^n} h(u, v) := \eta \sum_{i, j} \exp\left(\frac{u_i + v_j - C_{ij}}{\eta}\right) + \tau \langle e^{-u/\tau}, \mathbf{a} \rangle + \tau \langle e^{-v/\tau}, \mathbf{b} \rangle.$$

Let $(u^*, v^*) = \arg \min_{u, v \in \mathbb{R}^n} h(u, v)$, then the solution for the UOT problem is given by $X^* = \text{diag}(e^{u^*/\eta}) e^{\frac{-C}{\eta}} \text{diag}(e^{v^*/\eta})$, where $\text{diag}(x)$ denotes the diagonal matrix with x on the diagonal.

- The **Sinkhorn algorithm** optimizes the dual function by alternating descent algorithm.

Denote $B(u, v) = \text{diag}(e^{u/\eta})e^{-\frac{C}{\eta}}\text{diag}(e^{v/\eta})$.

Algorithm 1: UNBALANCED_SINKHORN

Input: marginals \mathbf{a} and \mathbf{b} , cost matrix C , accuracy ε .

Set $k = 0$ and $u^0 = v^0 = 0$ and a predefined η

while not StoppingCondition(k) do

$$a^k = B(u^k, v^k)\mathbf{1}_n.$$

$$b^k = B(u^k, v^k)^\top \mathbf{1}_n.$$

if k is even **then**

$$u^{k+1} = \left[\frac{u^k}{\eta} + \log(\mathbf{a}) - \log(a^k) \right] \frac{\eta\tau}{\eta + \tau}$$

$$v^{k+1} = v^k$$

else

$$v^{k+1} = \left[\frac{v^k}{\eta} + \log(\mathbf{b}) - \log(b^k) \right] \frac{\eta\tau}{\eta + \tau}$$

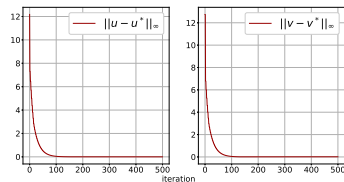
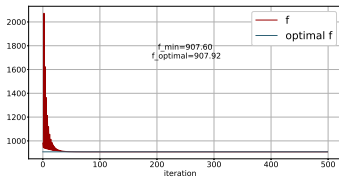
$$u^{k+1} = u^k.$$

end if

$$k = k + 1.$$

end while

Output: $B(u^k, v^k)$.



Convergence of Sinkhorn algorithm.

$$\eta = 0.05, \tau = 1, n = 100.$$

- Highly parallelizable.
- Can observe that the Sinkhorn solutions converge quickly.

ε -approximation

For any $\varepsilon > 0$, we call X an ε -approximation transportation plan if the following holds

$$\begin{aligned} & \langle C, X \rangle + \tau \mathbf{KL}(X \mathbf{1}_n \| \mathbf{a}) + \tau \mathbf{KL}(X^\top \mathbf{1}_n \| \mathbf{b}) \\ & \leq \langle C, \hat{X} \rangle + \tau \mathbf{KL}(\hat{X} \mathbf{1}_n \| \mathbf{a}) + \tau \mathbf{KL}(\hat{X}^\top \mathbf{1}_n \| \mathbf{b}) + \varepsilon, \end{aligned}$$

where \hat{X} is an optimal transportation plan for the UOT problem.

- **Complexity analysis:** Seek the value of η and corresponding k for which Sinkhorn algorithm reaches an ε -approximate solution.

Complexity analysis of OT is rather well-studied:

- Linear programming: $\tilde{O}(n^3)$ [Pele and Werman, 2009], $\tilde{O}(n^{5/2})$ [Lee and Sidford, 2014]
- Entropic regularization:
 - $\tilde{O}(n^2/\varepsilon^3)$ [Altschuler, Weed, and Rigollet, 2017], $\tilde{O}\left(\min\left(\frac{n^{9/4}}{\varepsilon}, \frac{n^2}{\varepsilon^2}\right)\right)$ [Dvurechenskii et al., 2018], $\tilde{O}(n^2/\varepsilon^2)$ [Lin, Ho, and Jordan, 2019a], $\tilde{O}(n^{7/3}/\varepsilon)$ [Lin, Ho, and Jordan, 2019b]
 - $\tilde{O}(n^{2.5}/\varepsilon)$ [Guo, Ho, and Jordan, 2019], $\tilde{O}(n^2/\varepsilon)$ [Jambulapati, Sidford, and Tian, 2019; Blanchet et al., 2018]

Key challenge with UOT

Previous analyses (e.g. [Chizat et al., 2016], [Sejourne et al., 2019]) have not addressed the **complexity of Sinkhorn algorithm** for approximating the exact UOT solution.

Our contribution

- Our contribution is a **bound of the number of iterations** that Sinkhorn algorithm requires to reach an ε -approximation solution of the UOT problem.

Main theorem

For $\eta = \varepsilon/\mathcal{O}(\log(n))$ and $k = \tilde{\mathcal{O}}(1/\varepsilon)$ (total complexity is $\tilde{\mathcal{O}}(n^2/\varepsilon)$), the update X^k from Sinkhorn algorithm is an ε -approximation of the optimal solution \hat{X} .

Remark

Compared to OT, for a similar order of n , we are better than [Dvurechensky, Gasnikov, and Kroshnin, 2018] by a factor of ε , while for a similar order of ε , we are better than [Lin, Ho, and Jordan, 2019b] by a factor of $n^{1/3}$.

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Convergence rate of the dual solution

Theorem 1

For any $k \geq 0$, the update (u^{k+1}, v^{k+1}) from Sinkhorn algorithm satisfies the following bound

$$\max \left\{ \|u^{k+1} - u^*\|_\infty, \|v^{k+1} - v^*\|_\infty \right\} \leq \left(\frac{\tau}{\tau + \eta} \right)^k \tau R,$$

where $R = \max \{ \|\log(\mathbf{a})\|_\infty, \|\log(\mathbf{b})\|_\infty \} + \max \left\{ \log(n), \frac{1}{\eta} \|C\|_\infty - \log(n) \right\}$.

Remark

The dual solution (u^k, v^k) has a **geometric convergence rate**, which depends explicitly on the number of components n and all other parameters of masses and penalty function.

Detailed bound on k

We state the main theorem with quantities S, T, U defined as

$$S = \frac{1}{2}(\alpha + \beta) + \frac{1}{2} + \frac{1}{4 \log(n)}, \quad S = \mathcal{O}(\alpha + \beta)$$

$$T = \left(\frac{\alpha + \beta}{2}\right) \left[\log\left(\frac{\alpha + \beta}{2}\right) + 2 \log(n) - 1 \right] + \log(n) + \frac{5}{2}, \quad T = \mathcal{O}((\alpha + \beta) \log(n))$$

$$U = \max \left\{ S + T, 2\varepsilon, \frac{4\varepsilon \log(n)}{\tau}, \frac{4\varepsilon(\alpha + \beta) \log(n)}{\tau} \right\}, \quad U = \mathcal{O}((\alpha + \beta) \log(n))$$

Theorem 2

For $\eta = \frac{\varepsilon}{U}$ and $k \geq 1 + \left(\frac{\tau U}{\varepsilon} + 1\right) \left[\log(8\eta R) + \log(\tau(\tau + 1)) + 3 \log\left(\frac{U}{\varepsilon}\right) \right]$, the update X^k from Algorithm 1 is an ε -approximation of the optimal solution \hat{X} .

Remark

$$k = \mathcal{O}\left(\frac{\tau(\alpha + \beta)}{\varepsilon} \log(n)\right)$$

Proof sketch of Theorem 2

With the defined k , we will prove that $f(X^k) - f(\hat{X}) \leq \varepsilon$ by showing that

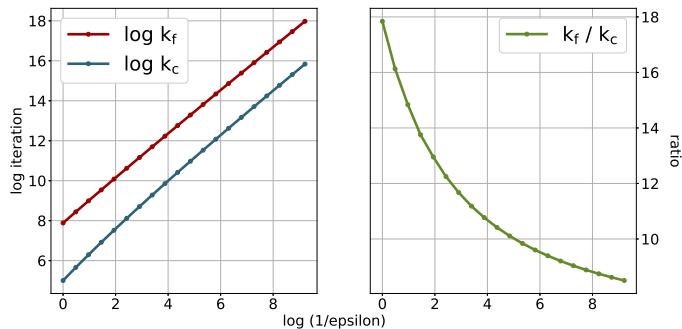
$$f(X^k) - f(\hat{X}) \leq [g(X^k) - g(X^*)] + \eta [H(X^k) - H(\hat{X})] \leq \varepsilon,$$

which comes from the fact that

- $g(X^k) - g(X^*) \leq \eta S$,
- $H(X^k) - H(\hat{X}) \leq T$,
- and combining these two bounds with the inequality $\eta = \frac{\varepsilon}{U} \leq \frac{\varepsilon}{S+T}$.

Experiment

k_f : given by our formula; k_c : the empirical lower-bound iteration for ε -approximation



$n = 100$; $\alpha = 2$, $\beta = 4$; $a_i, b_j \sim \mathcal{U}[0.1, 1]$; $C_{ij} \sim \mathcal{U}[1, 50]$; $\varepsilon = \text{LinSpace}(0.0001, 1)$

Thank you for your attention!

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